CS 3651 Skill Demo #6 Light Sensor Plus Whisker Navigation

Student Name:

Student GTID:

Follow pages 143-216 in the BoeBot book

**Task 1: Combine Light Sensor and Whiskers for Navigation**
Demonstrate robot behavior that includes navigation towards light as well as response to whisker-detected obstacles.

You are successful when your robot can drive autonomously from one of the starting blocks to the finish line near the light.

Behavior is correct ____

TA/Instructor initials_____________ date________________